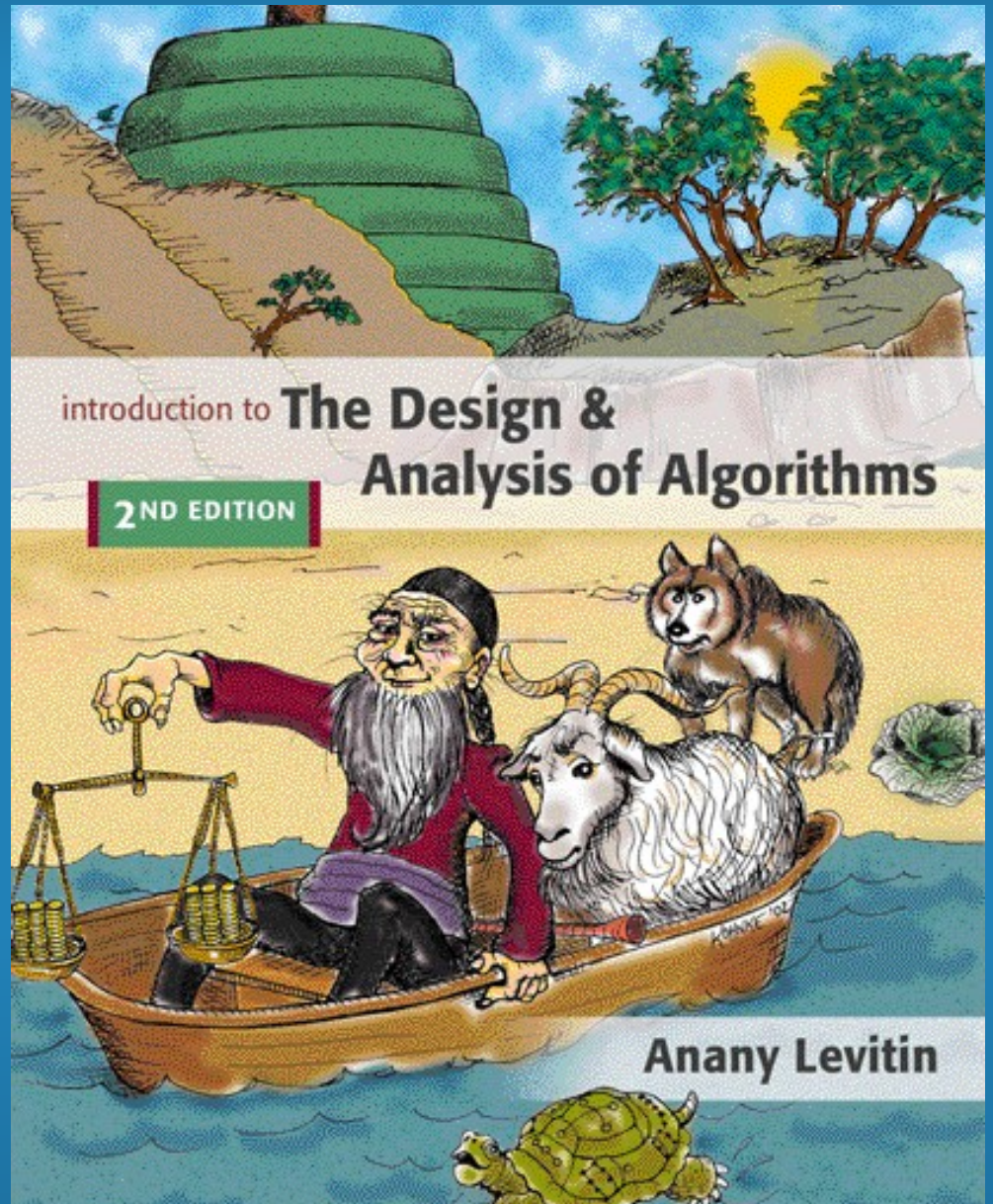
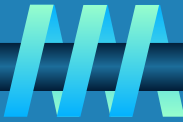


# Chapter 1

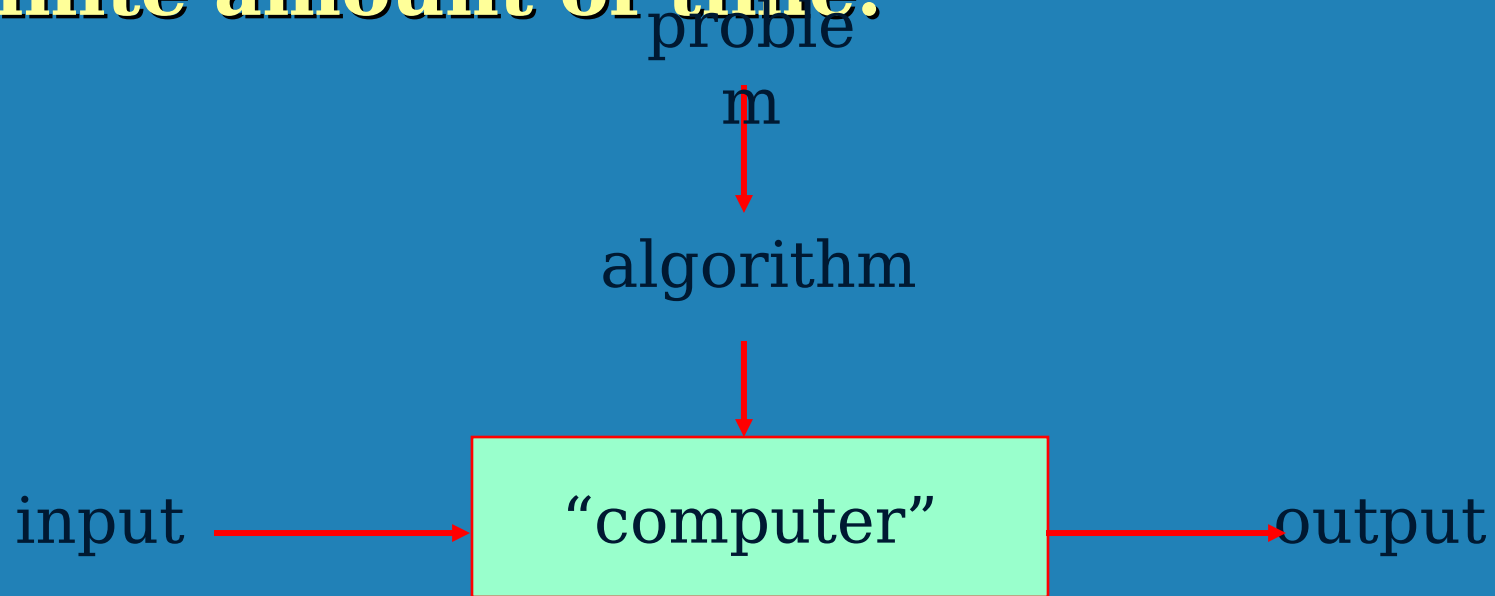
## Introduction



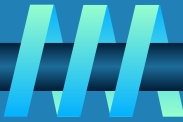
# What is an algorithm?



An algorithm is a sequence of unambiguous instructions for solving a problem, i.e., for obtaining a required output for any **legitimate** input in a finite amount of time.



# Algorithm



• **An algorithm is a sequence of unambiguous instructions for solving a problem, i.e., for obtaining a required output for any legitimate input in a finite amount of time.**

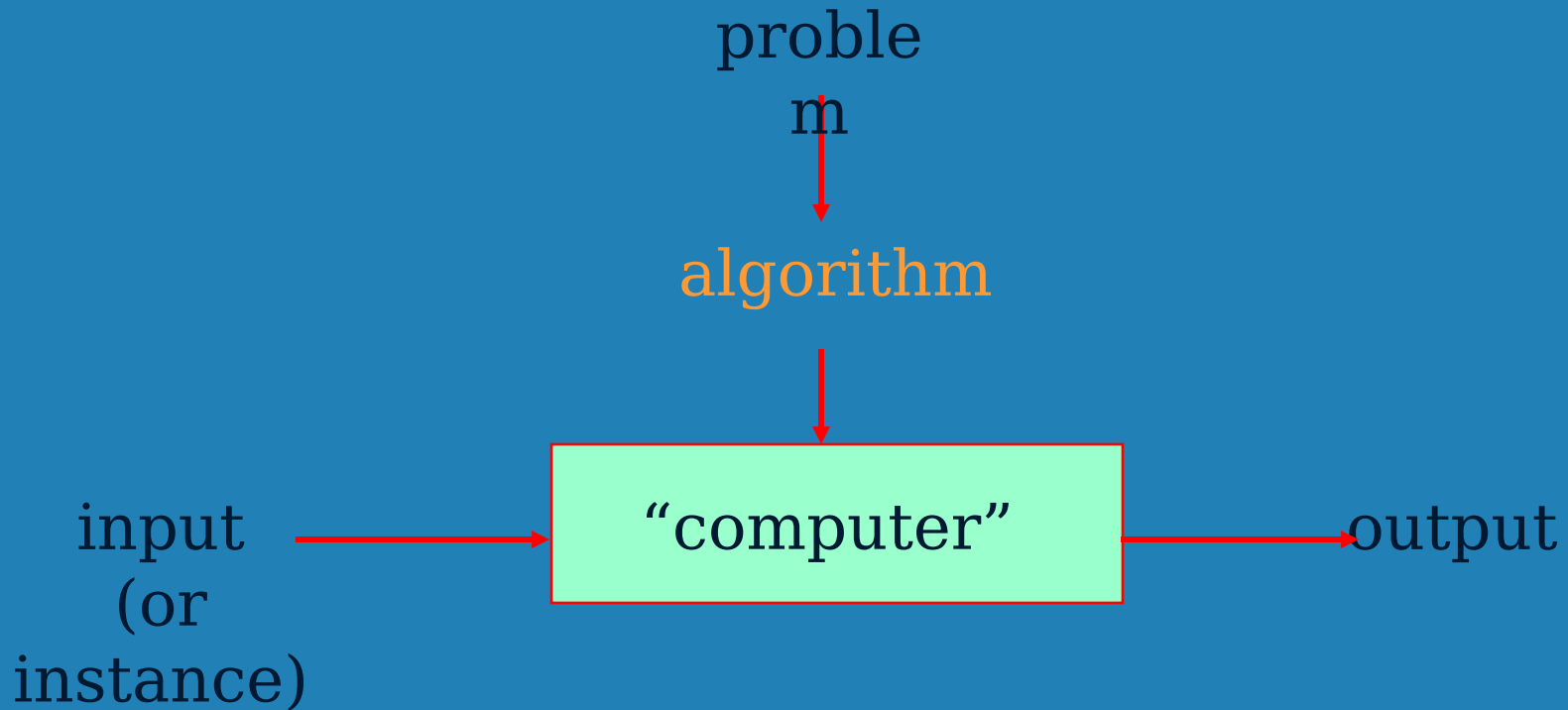
- Can be represented various forms
- Unambiguity/clarity
- Effectiveness
- Finiteness/termination
- Correctness

# Historical Perspective



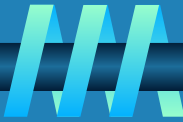
- **Euclid's algorithm for finding the greatest common divisor**
- ▮ **Muhammad ibn Musa al-Khwarizmi - 9<sup>th</sup> century mathematician**  
**[www.lib.virginia.edu/science/parshall/khwari z.html](http://www.lib.virginia.edu/science/parshall/khwari z.html)**

# Notion of algorithm and problem



algorithmic solution  
(different from a conventional solution)

# Example of computational problem: sorting



## ⚙ Statement of problem:

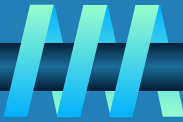
- **Input:** A sequence of  $n$  numbers  $\langle a_1, a_2, \dots, a_n \rangle$
- **Output:** A reordering of the input sequence  $\langle a'_1, a'_2, \dots, a'_n \rangle$  so that  $a'_i \leq a'_j$  whenever  $i < j$

▢ **Instance:** The sequence  $\langle 5, 3, 2, 8, 3 \rangle$

## ▢ Algorithms:

- Selection sort
- Insertion sort
- Merge sort
- (many others)

# Selection Sort



- Input: array  $a[1], \dots, a[n]$
- Output: array  $a$  sorted in non-decreasing order
- Algorithm:

```
for  $i=1$  to  $n$   
    swap  $a[i]$  with smallest of  $a[i], \dots, a[n]$ 
```

- Is this unambiguous? Effective?
- See also pseudocode, section 3.1

# Some Well-known Computational Problems



- ▮ **Sorting**
- ▮ **Searching**
- ▮ **Shortest paths in a graph**
- ▮ **Minimum spanning tree**
- ▮ **Primality testing**
- ▮ **Traveling salesman problem**
- ▮ **Knapsack problem**
- ▮ **Chess**
- ▮ **Towers of Hanoi**
- ▮ **Program termination**

Some of these problems don't have efficient algorithms, or algorithms at all!

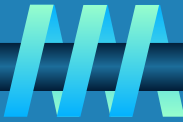


# Basic Issues Related to Algorithms



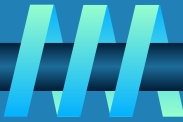
- ▮ **How to design algorithms**
- ▮ **How to express algorithms**
- ▮ **Proving correctness**
- ▮ **Efficiency (or complexity) analysis**
  - **Theoretical analysis**
  - **Empirical analysis**
- ▮ **Optimality**

# Algorithm design strategies



- ❁ **Brute force**
- ▮ **Divide and conquer**
- ▮ **Decrease and conquer**
- ▮ **Transform and conquer**
- ▮ **Greedy approach**
- ▮ **Dynamic programming**
- ▮ **Backtracking and branch-and-bound**
- ▮ **Space and time tradeoffs**

# Analysis of Algorithms



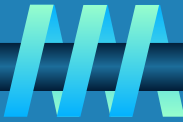
- ▮ **How good is the algorithm?**
  - **Correctness**
  - **Time efficiency**
  - **Space efficiency**
  
- ▮ **Does there exist a better algorithm?**
  - **Lower bounds**
  - **Optimality**

# What is an algorithm?



- ▮ **Recipe, process, method, technique, procedure, routine,... with the following requirements:**
  - 1. Finiteness**
    - ▮ terminates after a finite number of steps
  - 2. Definiteness**
    - ▮ rigorously and unambiguously specified
  - 3. Clearly specified input**
    - ▮ valid inputs are clearly specified
  - 4. Clearly specified/expected output**
    - ▮ can be proved to produce the correct output given a valid input
  - 5. Effectiveness**
    - ▮ steps are sufficiently simple and basic

# Why study algorithms?



## ▮ Theoretical importance

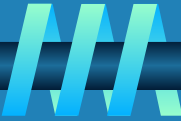
- the core of computer science

## ▮ Practical importance

- A practitioner's toolkit of known algorithms
- Framework for designing and analyzing algorithms for new problems

Example: Google's PageRank  
Technology

# Euclid's Algorithm



**Problem:** Find  $\text{gcd}(m,n)$ , the greatest common divisor of two nonnegative, not both zero integers  $m$  and  $n$

**Examples:**  $\text{gcd}(60,24) = 12$ ,  $\text{gcd}(60,0) = 60$ ,  
 $\text{gcd}(0,0) = ?$

**Euclid's algorithm is based on repeated application of equality**

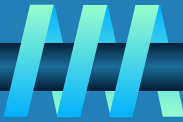
$$\text{gcd}(m,n) = \text{gcd}(n, m \bmod n)$$

**until the second number becomes 0, which makes the problem trivial.**

**Example:**  $\text{gcd}(60,24) = \text{gcd}(24,12) = \text{gcd}(12,0) = 12$



# Two descriptions of Euclid's algorithm



**Step 1** If  $n = 0$ , return  $m$  and stop; otherwise go to Step 2

**Step 2** Divide  $m$  by  $n$  and assign the value of the remainder to  $r$

**Step 3** Assign the value of  $n$  to  $m$  and the value of  $r$  to  $n$ . Go to Step 1.

**while**  $n \neq 0$  **do**

$r \leftarrow m \bmod n$

$m \leftarrow n$

$n \leftarrow r$

**return**  $m$

# Other methods for computing $\text{gcd}(m, n)$



## Consecutive integer checking algorithm

**Step 1** Assign the value of  $\min\{m, n\}$  to  $t$

**Step 2** Divide  $m$  by  $t$ . If the remainder is 0, go to Step 3;  
otherwise, go to Step 4

**Step 3** Divide  $n$  by  $t$ . If the remainder is 0, return  $t$  and stop;  
otherwise, go to Step 4

**Step 4** Decrease  $t$  by 1 and go to Step 2

Is this slower than Euclid's algorithm? How much slower?

$O(n)$ , if  $n \leq m$ , vs  $O(\log n)$



# Other methods for $\text{gcd}(m,n)$ [cont.]



## Middle-school procedure

**Step 1** Find the prime factorization of  $m$

**Step 2** Find the prime factorization of  $n$

**Step 3** Find all the common prime factors

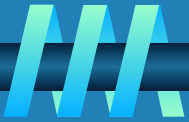
**Step 4** Compute the product of all the  
common prime factors  
and return it as  $\text{gcd}(m,n)$

Is this an algorithm?

How efficient is it?

Time complexity:  
 $O(\sqrt{n})$

# Sieve of Eratosthenes



Input: Integer  $n \geq 2$

Output: List of primes less than or equal to  $n$

**for**  $p \leftarrow 2$  **to**  $n$  **do**  $A[p] \leftarrow p$

**for**  $p \leftarrow 2$  **to**  $n$  **do**

**if**  $A[p] \neq 0$  //  $p$  hasn't been previously eliminated from the list

$j \leftarrow p * p$

**while**  $j \leq n$  **do**

$A[j] \leftarrow 0$  //mark element as eliminated

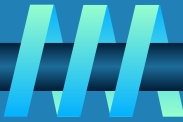
$j \leftarrow j + p$

**Example:** 2 3 4 5 6 7 8 9 10 11 12 13 14 15  
16 17 18 19 20

Time complexity:

$O(n)$

# Two main issues related to algorithms



- ▮ **How to design algorithms**
- ▮ **How to analyze algorithm efficiency**



# Algorithm design techniques/strategies



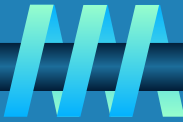
## ⚙ **Brute force**

- ▢ **Divide and conquer**
- ▢ **Decrease and conquer**
- ▢ **Transform and conquer**
- ▢ **Space and time tradeoffs**

## ⚙ **Greedy approach**

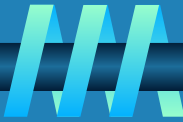
- ▢ **Dynamic programming**
- ▢ **Iterative improvement**
- ▢ **Backtracking**
- ▢ **Branch and bound**

# Analysis of algorithms



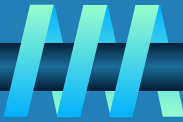
- ▮ **How good is the algorithm?**
  - time efficiency
  - space efficiency
  - **correctness ignored in this course**
  
- ▮ **Does there exist a better algorithm?**
  - lower bounds
  - optimality

# Important problem types



- ▮ **sorting**
- ▮ **searching**
- ▮ **string processing**
- ▮ **graph problems**
- ▮ **combinatorial problems**
- ▮ **geometric problems**
- ▮ **numerical problems**

# Sorting (I)



- ▮ **Rearrange the items of a given list in ascending order.**
  - **Input:** A sequence of  $n$  numbers  $\langle a_1, a_2, \dots, a_n \rangle$
  - **Output:** A reordering  $\langle a'_1, a'_2, \dots, a'_n \rangle$  of the input sequence such that  $a'_1 \leq a'_2 \leq \dots \leq a'_n$ .
- ▮ **Why sorting?**
  - **Help searching**
  - **Algorithms often use sorting as a key subroutine.**
- ▮ **Sorting key**
  - **A specially chosen piece of information used to guide sorting. E.g., sort student records by names.**

# Sorting (II)



## ▮ Examples of sorting algorithms

- Selection sort
- **Bubble sort**
- **Insertion sort**
- **Merge sort**
- **Heap sort ...**

## ▮ Evaluate sorting algorithm complexity: the number of key comparisons.

## ▮ Two properties

- **Stability:** A sorting algorithm is called stable if it preserves the relative order of any two equal elements in its input.
- **In place :** A sorting algorithm is in place if it does not require extra memory, except, possibly for a few memory units.



# Selection Sort



Algorithm *SelectionSort(A[0..n-1])*

**//The algorithm sorts a given array by selection sort**

**//Input: An array A[0..n-1] of orderable elements**

**//Output: Array A[0..n-1] sorted in ascending order**

**for i  $\leftarrow$  0 to n - 2 do**

**min  $\leftarrow$  i**

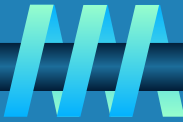
**for j  $\leftarrow$  i + 1 to n - 1 do**

**if A[j] < A[min]**

**min  $\leftarrow$  j**

**swap A[i] and A[min]**

# Searching



Find a given value, called a search key, in a given set.

Examples of searching algorithms

- Sequential search

- Binary search ...

Input: sorted array  $a_i < \dots < a_j$  and key  $x$ ;

$m \leftarrow (i+j)/2$ ;

while  $i < j$  and  $x \neq a_m$  do

    if  $x < a_m$  then  $j \leftarrow m-1$

        else  $i \leftarrow m+1$ ;

if  $x = a_m$  then output  $a_m$ ;

# String Processing



- ▮ **A string is a sequence of characters from an alphabet.**
- ▮ **Text strings: letters, numbers, and special characters.**
- ▮ **String matching: searching for a given word/pattern in a text.**

Examples:

- (i) searching for a word or phrase on WWW or in a Word document
- (ii) searching for a short read in the reference genomic sequence

# Graph Problems



- **Informal definition**

- A graph is a collection of points called **vertices**, some of which are connected by line segments called **edges**.

- ▮ **Modeling real-life problems**

- Modeling WWW
- Communication networks
- Project scheduling ...

- ▮ **Examples of graph algorithms**

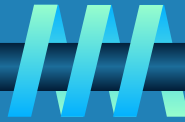
- Graph traversal algorithms
- Shortest-path algorithms
- Topological sorting

# Fundamental data structures



- ⊗ **list**
  - **array**
  - **linked list**
  - **string**
- ▮ **stack**
- ▮ **queue**
- ▮ **priority queue/heap**
- ▮ **graph**
- ▮ **tree and binary tree**
- ▮ **set and dictionary**

# Linear Data Structures



## • Arrays

- A sequence of  $n$  items of the same data type that are stored contiguously in computer memory and made accessible by specifying a value of the array's index.

## ▣ Linked List

- A sequence of zero or more nodes each containing two kinds of information: some data and one or more links called pointers to other nodes of the linked list.
- **Singly linked list (next pointer)**
- **Doubly linked list (next + previous pointers)**



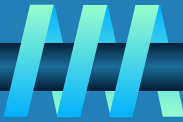
## ■ Arrays

- fixed length (need preliminary reservation of memory)
- contiguous memory locations
- direct access
- Insert/delete

## Linked Lists

- dynamic length
- arbitrary memory locations
- access by following links
- Insert/delete

# Stacks and Queues



## Stacks

- A stack of plates
  - insertion/deletion can be done only at the top.
  - LIFO
- Two operations (push and pop)

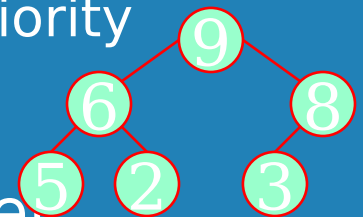
## Queues

- A queue of customers waiting for services
  - Insertion/enqueue from the rear and deletion/dequeue from the front.
  - FIFO
- Two operations (enqueue and dequeue)

# Priority Queue and Heap



- **Priority queues** (implemented using **heaps**)
  - A data structure for maintaining a **set** of elements, each associated with a key/priority, with the following operations
    - Finding the element with the highest priority
    - Deleting the element with the highest priority
    - Inserting a new element
  - Scheduling jobs on a shared computer





# Graphs



## Formal definition

- A graph  $G = \langle V, E \rangle$  is defined by a pair of two sets: a finite set  $V$  of items called **vertices** and a set  $E$  of vertex pairs called **edges**.

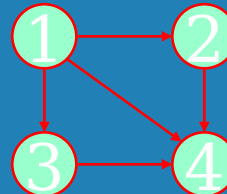
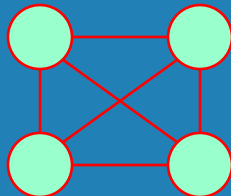
## Undirected and directed graphs (digraphs).

## What's the maximum number of edges in an undirected graph with $|V|$ vertices?

## Complete, dense, and sparse graphs

- A graph with every pair of its vertices connected by an edge is called **complete**,

$K_{|V|}$



# Graph Representation



## • Adjacency matrix

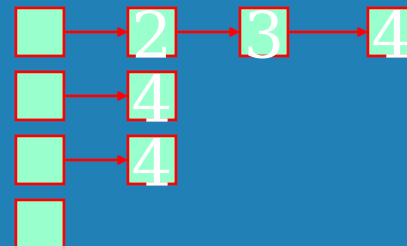
- $n \times n$  boolean matrix if  $|V|$  is  $n$ .
- The element on the  $i$ th row and  $j$ th column is 1 if there's an edge from  $i$ th vertex to the  $j$ th vertex; otherwise 0.
- The adjacency matrix of an undirected graph is symmetric.

## ▢ Adjacency linked lists

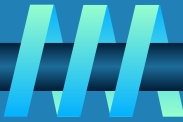
- A collection of linked lists, one for each vertex, that contain all the vertices adjacent to the list's vertex.

## ▢ Which data structure would you use if the graph is a 100-node star shape?

0	1	1	1
0	0	0	1
0	0	0	1
0	0	0	0

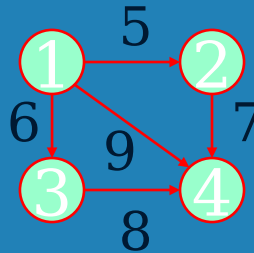


# Weighted Graphs



## ▮ **Weighted graphs**

- **Graphs or digraphs with numbers assigned to the edges.**



# Graph Properties -- Paths and Connectivity



## ▮ Paths

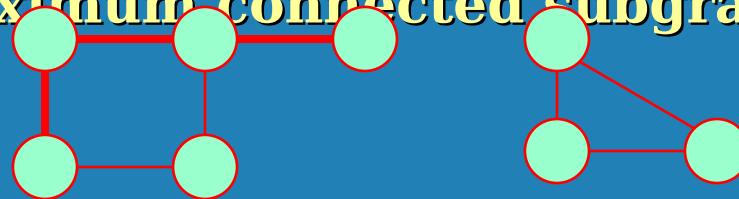
- A path from vertex  $u$  to  $v$  of a graph  $G$  is defined as a sequence of adjacent (connected by an edge) vertices that starts with  $u$  and ends with  $v$ .
- **Simple paths:** All edges of a path are distinct.
- Path lengths: the number of edges, or the number of vertices - 1.

## ▮ Connected graphs

- A graph is said to be connected if for every pair of its vertices  $u$  and  $v$  there is a path from  $u$  to  $v$ .

## ▮ Connected component

- The maximum connected subgraph of a given graph.



# Graph Properties -- Acyclicity

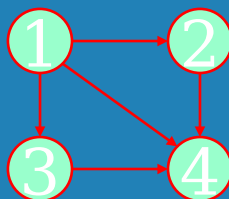


## □ Cycle

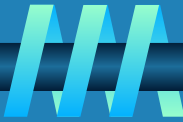
- A simple path of a positive length that starts and ends at the same vertex.

## □ Acyclic graph

- A graph without cycles
- **DAG** (Directed Acyclic Graph)



# Trees

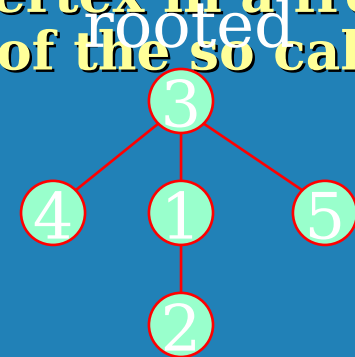


## Trees

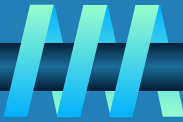
- A tree (or **free tree**) is a connected acyclic graph.
- Forest: a graph that has no cycles but is not necessarily connected.

## Properties of trees

- For every two vertices in a tree there always exists exactly one simple path from one of these vertices to the other. Why?
  - **Rooted trees**: The above property makes it possible to select an arbitrary vertex in a free tree and consider it as the root of the so called rooted tree.
- $|E| = |V| - 1$ 
  - Levels in a rooted tree.



# Rooted Trees (I)



## ❁ Ancestors

- For any vertex  $v$  in a tree  $T$ , all the vertices on the simple path from the root to that vertex are called ancestors.

## ❁ Descendants

- All the vertices for which a vertex  $v$  is an ancestor are said to be descendants of  $v$ .

## ▢ Parent, child and siblings

- If  $(u, v)$  is the last edge of the simple path from the root to vertex  $v$ ,  $u$  is said to be the parent of  $v$  and  $v$  is called a child of  $u$ .
- Vertices that have the same parent are called siblings.

## ▢ Leaves

- A vertex without children is called a leaf.

## ▢ Subtree

- A vertex  $v$  with all its descendants is called the subtree of  $T$  rooted at  $v$ .

# Rooted Trees (II)

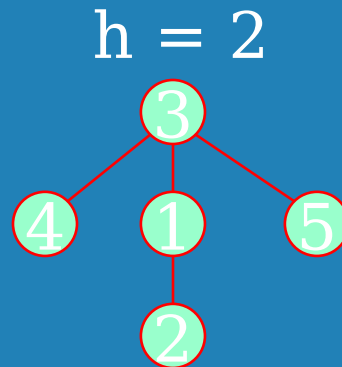


## □ **Depth** of a vertex

- The length of the simple path from the root to the vertex.

## □ **Height** of a tree

- The length of the longest simple path from the root to a leaf.





# Ordered Trees



## ❁ Ordered trees

- An ordered tree is a rooted tree in which all the children of each vertex are ordered.

## ▮ Binary trees

- A binary tree is an ordered tree in which every vertex has no more than two children and each children is designated as either a left child or a right child of its parent.

## ▮ Binary search trees

- Each vertex is assigned a number.
- A number assigned to each parental vertex is larger than all the numbers in its left subtree and smaller than all the numbers in its right subtree.

- ▮  $\lfloor \log_2 n \rfloor \leq h \leq n - 1$ , where  $h$  is the height of a binary tree and  $n$  the size.

